



goodtech

# Integration of vision-based control and multimodal interfaces for a collaborative industrial robot



ABB:s YuMi®  
(photo: ABB.com)

In this project, we are aiming to enable an industrial robot to collaborate with humans in order to accomplish a task, where different kind of sensors and multimodal interfaces can be integrated. In this project, special focus will be given to design and implementation of an application for a collaborative industrial robot.