Stochastic homogenization of multicontinuum models

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- Introduction to the models
- Literature to averaging
- Introduction to homogenization
- Main results
- Some proofs
- Some remarks

$$\frac{\partial u^{\varepsilon}}{\partial t}(t,x) = \nabla \cdot \left[A(\frac{x}{\varepsilon}, v^{\varepsilon})\nabla u^{\varepsilon}(t,x)\right] + \text{additional terms}
dv^{\varepsilon}(t,x) = -\frac{1}{\varepsilon}(v^{\varepsilon}(t,x) - u^{\varepsilon}(t,x))dt + \sqrt{\frac{Q}{\varepsilon}}dW(t,x),$$
(1)

 $A(\cdot, \cdot)$ is the permeability of the medium, Q is a bounded linear operator of trace class defined on $L^2(D)$ and W a standard $L^2(D)$ -valued Brownian motion.

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- Here we have time scale and spatial scale: $(t, \frac{t}{\epsilon})$ and $(x, \frac{x}{\epsilon})$.
- v^{ε} is the fast variable while u^{ε} is the slow variable.
- Then the goal is to pass to the limit in ε .
- To find the homogenized (effective) equation.

$$\begin{aligned} \frac{\partial u^{\varepsilon}}{\partial t}(t,x) &= \operatorname{div}\left(A\left(\frac{x}{\varepsilon}\right)\nabla u^{\varepsilon}(t,x)\right) + \alpha\left(\frac{x}{\varepsilon},v^{\varepsilon}(t,x)\right)u^{\varepsilon}(t,x) + f(t,x)\\ dv^{\varepsilon}(t,x) &= -\frac{1}{\varepsilon}(v^{\varepsilon}(t,x) - u^{\varepsilon}(t,x))dt + \sqrt{\frac{Q}{\varepsilon}}dW(t,x), \end{aligned}$$

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$$\begin{aligned} \frac{\partial u^{\varepsilon}}{\partial t}(t,x) &= \operatorname{div}\left(A\left(\frac{x}{\varepsilon}\right)\nabla u^{\varepsilon}(t,x)\right) + \alpha\left(\frac{x}{\varepsilon},v^{\varepsilon}(t,x)\right)\nabla u^{\varepsilon}(t,x) + f(t,x)\\ dv^{\varepsilon}(t,x) &= -\frac{1}{\varepsilon}(v^{\varepsilon}(t,x) - u^{\varepsilon}(t,x))dt + \sqrt{\frac{Q}{\varepsilon}}dW(t,x), \end{aligned}$$

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Multicontinuum model

$$\frac{\partial u_1^{\varepsilon}}{\partial t} = \operatorname{div} \left(A_1^{\varepsilon} \nabla u_1^{\varepsilon} \right) + \alpha^{\varepsilon} \left(v_1^{\varepsilon}, v_2^{\varepsilon} \right) \left(u_2^{\varepsilon} - u_1^{\varepsilon} \right) + f_1,$$

$$\begin{split} \frac{\partial u_2^{\varepsilon}}{\partial t} &= \operatorname{div} \left(A_2^{\varepsilon} \nabla u_2^{\varepsilon} \right) + \alpha^{\varepsilon} \left(v_1^{\varepsilon}, v_2^{\varepsilon} \right) \left(u_1^{\varepsilon} - u_2^{\varepsilon} \right) + f_2, \\ dv_1^{\varepsilon} &= -\frac{1}{\varepsilon} (v_1^{\varepsilon} - g_1(u_1^{\varepsilon}, u_2^{\varepsilon}) dt + \sqrt{\frac{Q_1}{\varepsilon}} dW_1(t, x), \\ dv_2^{\varepsilon} &= -\frac{1}{\varepsilon} (v_2^{\varepsilon} - g_2(u_1^{\varepsilon}, u_2^{\varepsilon}) dt + \sqrt{\frac{Q_2}{\varepsilon}} dW_2(t, x) \\ &+ \operatorname{Boundary Conditions, Initial Conditions, \end{split}$$

where g_1 , g_2 are Lipschitz.

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Is For stochastic differential equations:

- R.Z. Khasminskii, on the principle of averaging the Itô stochastic differential equation, Kybernetika, (1968).
- A.Yu. Veretennikov, On the averaging principle for systems of stochastic differential equations, Mat. USSR Sb., (1991).
- M. Freidlin, A. Wentzell, *Averaging principle for stochastic perturbations of multifrequency systems*, Stochastics and Dynamics, (2003).
- Por stochastic partial differential equations:
 - S. Cerrai, A Khasminskii type averaging principle for stochastic reaction-diffusion equations, Ann. Appl. Probab., (2009)
 - S. Cerrai, M. Freidlin, *Averaging principle for a class of stochastic reaction-diffusion equations*, Probab. Theory Related Fields, (2009).

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Assume to have a sequence of partial differential operators L_{ε} (with oscillating coefficients) and a sequence of solutions u_{ε} which for a given domain D and source f

$$L_{\varepsilon}u_{\varepsilon} = f \quad in \ D \tag{2}$$

complemented by appropriate boundary conditions. If we assume that u_{ε} converges in some sense to some u, we look for a so-called homogenized operator \overline{L} such that

$$\overline{L}u = f \quad in \ D \tag{3}$$

Passing from (2) to (3) is the homogenization process.

Typically

$$L_{\varepsilon}u^{\varepsilon}=-
abla\cdot(a(x,\frac{x}{\varepsilon})
abla u^{\varepsilon}).$$

Formally, in order to find the form of \overline{L} , one writes the expansion

$$u_{\varepsilon}(x) = u_0(x, \frac{x}{\varepsilon}) + \varepsilon u_1(x, \frac{x}{\varepsilon}) + \varepsilon^2 u_2(x, \frac{x}{\varepsilon}) + \dots$$
(4)

where each $u_i(x, y)$ is periodic in y. Inserting (4) into (2) leads to a cascade of equations for u_i and averaging wrt to y the equation for u_0 gives (3).

Typically

$$\overline{L}u_0(x) = -\nabla \cdot (\overline{a}(x)\nabla u_0(x)),$$

where

$$\overline{a}(x) = \int_{Y} \langle a(x,y)(I + \nabla_{y}N), (I + \nabla_{y}N) \rangle dy,$$

such that N is solution of the cell problem:

$$-\operatorname{div}(a(I + \nabla N)) = 0$$
 in Y

and $y \to N(x, y)$ - is Y periodic. Now, other arguments are needed to prove the convergence of the sequence u_{ε} to u_0 .

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- The energy method
- 2 The two-scale convergence

Literature on homogenization

Interpretation of the Stokes problem in perforated domains

- Sánchez-Palencia (1980) (asymptotic expansion method)
- L. Tartar (the energy method)
- G. Allaire (1992) (two scale convergence method)
- Homogenization of PDEs with random coefficients or stochastic forcing in non perforated domains
 - Bourgeat, A. Mikelić and Wright in (1994)
 - P. A. Razafimandimby, M. Sango, and J. L. Woukeng (2012)
- Homogenization of SPDEs in perforated domains (at its infancy)
 - W. Wang and J. Duan (2007)
 - H. Bessaih, Y. Efendiev and F. Maris (2015, 2016)

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The α satisfies the following conditions:

$$\alpha(\cdot, x) \in L^2_{per}(Y), \tag{5}$$

for every $x \in \mathbb{R}^3$.

$$\alpha(\mathbf{y},\cdot)\in Lip_b(\mathbb{R}),\tag{6}$$

for every $y \in Y$, with

$$\|\alpha(\mathbf{y},\cdot)\|_{Lip_b(\mathbb{R})} \le C,\tag{7}$$

The matrix $A = (a_{ij})_{1 \le i,j \le 3} \in L^{\infty}(Y; \mathbb{R}^{3 \times 3})$ is strictly positive and bounded uniformly in $y \in Y$, i. e. there exist 0 < m < M such that

$$m\xi^2 \le A(y)\xi\xi \le M\xi^2,\tag{8}$$

for almost every $y \in Y$ and $\xi \in \mathbb{R}^3$.

For any $\varepsilon > 0$, we denote by

$$A^{\varepsilon}: \mathbb{R}^3 \to \mathbb{R}^{3 \times 3}, \quad A^{\varepsilon}(x) = A\left(\frac{x}{\varepsilon}\right),$$
 (9)

and

$$\alpha^{\varepsilon}: L^{2}(D) \to L^{\infty}(D), \quad \alpha^{\varepsilon}(\eta)(x) = \alpha\left(\frac{x}{\varepsilon}, \eta(x)\right).$$
(10)

We assume that W is Bm on a filtered probability space $(\Omega, \mathcal{F}, \mathcal{F}_t, \mathbb{P})$. Q is a bounded operator on $L^2(D)$ of trace class, and that $f \in L^2(0, T; L^2(D))$ and $u_0^{\varepsilon}, v_0^{\varepsilon} \in L^2(D)$

E. Pardoux, A. L. Piatniski (2003), *Homogenization of a nonlinear* random parabolic partial differential equation

$$\begin{aligned} \frac{\partial u^{\varepsilon}}{\partial t} &= \nabla \cdot \left(A(\frac{x}{\varepsilon}, v(\frac{t}{\varepsilon^2})) \nabla u^{\varepsilon} \right) + \frac{1}{\varepsilon} g(\frac{x}{\varepsilon}, v(\frac{t}{\varepsilon^2}), u^{\varepsilon}) \\ dv &= b(v) dt + \sigma(v) dW, \end{aligned}$$

In Cerrai-Friedlin (2009), they consider

$$du = [A_1u + B_1(u, v)]dt + G_1(u, v)dW$$
$$dv = \frac{1}{\varepsilon}[A_2v + B_2(u, v)]dt + \frac{1}{\sqrt{\varepsilon}}G_2(u, v)dW.$$

Where B_1 and B_2 are Lipschitz-Continuous. In particular, our term $\alpha(\cdot, v^{\varepsilon})u^{\varepsilon}$ or $\alpha(\cdot, v^{\varepsilon})\nabla u^{\varepsilon}$ do not satisfy these assumptions. If $u_0^{\varepsilon} \in L^2(D)$ and $v_0^{\varepsilon} \in L^2(\Omega; L^2(D))$ then there exists a unique global solution $u^{\varepsilon} \in L^{\infty}(\Omega; C([0, T]; L^2(D) \cap L^2(0, T; H_0^1(D))))$ and $v^{\varepsilon} \in L^2(\Omega; C([0, T]; L^2(D)): \mathbb{P}$ a.s.

$$\int_{D} u^{\varepsilon}(t)\phi - \int_{D} u_{0}^{\varepsilon}\phi + \int_{0}^{t} \int_{D} \mathbf{A}^{\varepsilon} \nabla u^{\varepsilon}(s) \nabla \phi + \int_{0}^{t} \int_{D} \alpha^{\varepsilon}(\mathbf{v}^{\varepsilon}) u^{\varepsilon}\phi$$
$$= \int_{0}^{t} \int_{D} f(s)\phi,$$

for every $t \in [0, T]$ and every $\phi \in H_0^1(D)$, and

$$v^{\varepsilon}(t) = v_0^{\varepsilon} e^{-t/\varepsilon} + \frac{1}{\varepsilon} \int_0^t u^{\varepsilon}(s) e^{-(t-s)/\varepsilon} ds + \frac{1}{\sqrt{\varepsilon}} \int_0^t e^{-(t-s)/\varepsilon} dW(s).$$

$$\sup_{\varepsilon>0} \|u^{\varepsilon}\|_{L^{\infty}(\Omega; L^{2}(0, T; H^{1}_{0}(D)))} \leq C_{T},$$
(11)

$$\sup_{\varepsilon>0} \|u^{\varepsilon}\|_{L^{\infty}(\Omega; C([0,T]; L^{2}(D)))} \leq C_{T},$$
(12)

 and

$$\sup_{\varepsilon>0} \left\| \frac{\partial u^{\varepsilon}}{\partial t} \right\|_{L^{\infty}(\Omega; L^{2}(0, T; H^{-1}(D)))} \leq C_{T}.$$
 (13)

$$\sup_{\varepsilon>0} \mathbb{E} \sup_{t\in[0,T]} \|v^{\varepsilon}(t)\|_{L^{2}(D)}^{2} \leq C_{T}.$$
 (14)

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For fixed $\xi \in L^2(D)$:

$$\begin{cases} dv^{\xi} = -(v^{\xi} - \xi)dt + \sqrt{Q}dW, \\ v(0) = \eta. \end{cases}$$
(15)

This equation admits a unique mild solution $v^{\xi}(t) \in L^{2}(\Omega; C(0, T; L^{2}(D)))$ given by:

$$v^{\xi}(t) = \eta e^{-t} + \xi(1 - e^{-t}) + \int_0^t e^{-(t-s)} \sqrt{Q} dW.$$
 (16)

Let us define the transition semigroup P_t^{ξ} associated to the equation (15)

$$\mathsf{P}_t^{\xi} \Phi(\eta) = \mathbb{E} \Phi(\mathsf{v}^{\xi,\eta}(t)), \tag{17}$$

for every $\Phi \in B_b(L^2(D))$ and every $\eta \in L^2(D)$. Let μ^{ξ} be the associated invariant measure on $L^2(D)$. We recall that it is invariant for the semigroup P_t^{ξ} if

$$\int_{L^2(D)} P_t^{\xi} \Phi(z) d\mu^{\xi}(z) = \int_{L^2(D)} \Phi(z) d\mu^{\xi}(z)$$

for every $\Phi \in B_b(L^2(D))$.

The equation (15) admits a unique ergodic invariant measure μ^{ξ} that is strongly mixing and gaussian with mean ξ and operator Q. We also have:

$$\left| P_t^{\xi} \Phi(\eta) - \int_{L^2(D)} \Phi(z) d\mu^{\xi}(z)
ight| \leq c [\Phi] e^{-t} (1 + \|\eta\|_{L^2(D)} + \|\xi\|_{L^2(D)}),$$

for any Lipschitz function Φ defined on $L^2(D)$, where $[\Phi]$ is the Lipschitz constant of Φ .

We need more refined results for the fast motion equation.

So for any $\xi, \eta \in L^2(\Omega, \mathcal{F}_{t_0}, L^2(D))$, and a.e. $\omega \in \Omega$ we have:

$$\mathbb{E}\left(\|v^{\xi,\eta}(t)\|_{L^{2}(D)}^{2}|\mathcal{F}_{t_{0}}\right) \leq 2\left(\|\eta\|_{L^{2}(D)}^{2}e^{-2(t-t_{0})} + \|\xi\|_{L^{2}(D)}^{2} + \operatorname{Tr}Q\right),$$
 and

$$\mathbb{E}\left(\left|P_t^{\xi(\omega)}\Phi(\eta(\omega))-\int_{L^2(D)}\Phi(z)d\mu^{\xi(\omega)}(z)
ight|\left|\mathcal{F}_{t_0}
ight)\leq c[\Phi]e^{-(t-t_0)}(1+\|\eta(\omega)\|_{L^2(D)}+\|\xi(\omega)\|_{L^2(D)}),$$

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Lemma

Let $\Phi \in C^u([0, T]; L^{\infty}(\Omega; Lip(L^2(D))))$ be an \mathcal{F}_t - measurable process on $Lip(L^2(D))$, and let $0 \leq t_0 < t_0 + \delta \leq T$. For $\xi, \eta \in L^2(\Omega, \mathcal{F}_{t_0}, L^2(D))$, let $v^{\xi,\eta}$ be the previous solution. We have:

$$\mathbb{E}\left(\left|\frac{1}{\delta}\int_{t_{0}}^{t_{0}+\delta}\left(\Phi(s,v^{\xi,\eta}(s))-\int_{L^{2}(D)}\Phi(s,z)d\mu^{\xi}(z)\right)ds\right|\left|\mathcal{F}_{t_{0}}\right)\leq c\left(1+\|\eta\|_{L^{2}(D)}+\|\xi\|_{L^{2}(D)}\right)\left(\frac{\|\Phi\|}{\sqrt{\delta}}+\sqrt{\|\Phi\|[\Phi](\delta)}\right),$$
(18)

where $[\Phi]$ is the modulus of uniform continuity of Φ .

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This lemma is crucial because, we need to apply the semigroup P_t^ξ to a function of the form

$$\Phi^{arepsilon}(oldsymbol{s},\eta) = \int_D lpha^{arepsilon}(\eta) u^{arepsilon}\left(arepsilonoldsymbol{s}
ight) dx$$

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We introduce $\chi: Y \to \mathbb{R}$ the solution of the cell problem

$$\begin{cases} \operatorname{div} \left(A(y) \left(I + \nabla \chi(y) \right) \right) &= 0 & \text{in } Y, \\ \chi & -Y & \text{periodic,} \end{cases}$$

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We introduce the following averaged operators:

$$egin{aligned} \overline{lpha^arepsilon} &: L^2(D) o L^\infty(D), \ \ \overline{lpha^arepsilon}(\xi) &= \int_{L^2(D)} lpha^arepsilon(\eta) d\mu^{\xi}(\eta) \ \ \overline{lpha}(\xi) &= \int_{L^2(D)} \left(\int_Y lpha(y,z) dy
ight) d\mu^{\xi}(z). \ \ \overline{A} &= \int_Y A(y) \left(I +
abla \chi(y)
ight) dy. \end{aligned}$$

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Our main result of the diffusion reaction equation

Theorem (Bessaih-Efendiev-Maris, 2019)

Assume the sequence u_0^{ε} is uniformly bounded in $H_0^1(D)$) and strongly convergent in $L^2(D)$ to some function u_0 , and v_0^{ε} is uniformly bounded in $L^2(\Omega; L^2(D))$. Then, there exists $\overline{u} \in L^2(0, T; H_0^1(D))$) such that u^{ε} converges in probability to \overline{u} in $L^2(0, T; H_0^1(D))$) and \overline{u} is the solution of the following deterministic equation:

$$\begin{cases} \frac{\partial \overline{u}}{\partial t} = \operatorname{div}\left(\overline{A}\nabla\overline{u}\right) + \overline{\alpha}(\overline{u})\overline{u} + f & \text{in } D, \\ \overline{u} = 0 & \text{on } \partial D, \\ \overline{u}(0) = u_0 & \text{in } D. \end{cases}$$
(19)

Our main result of the convection diffusion equation

Theorem (Bessaih-Efendiev-Maris, 2020)

Assume the sequence u_0^{ε} is uniformly bounded in $H_0^1(D)$) and strongly convergent in $L^2(D)$ to some function u_0 , and v_0^{ε} is uniformly bounded in $L^2(\Omega; L^2(D))$. Then, there exists $\overline{u} \in L^2(0, T; H_0^1(D))$) such that u^{ε} converges in probability to \overline{u} in $L^2(0, T; H_0^s(D))$) where $0 \le s < 1$ and \overline{u} is the solution of the following deterministic equation:

$$\begin{cases} \frac{\partial \overline{u}}{\partial t} = \operatorname{div}\left(\overline{A}\nabla\overline{u}\right) + \overline{\alpha_{K}}(\overline{u})\nabla\overline{u} + f & \text{in } D, \\ \overline{u} = 0 & \text{on } \partial D, \\ \overline{u}(0) = u_{0} & \text{in } D. \end{cases}$$
(20)

 $\alpha_{\mathcal{K}}(\mathbf{y},\eta) = \alpha(\mathbf{y},\eta) \left(\mathbf{I} + \nabla \chi(\mathbf{y}) \right)$

Our main result of the multicontinuum equation

Theorem (Bessaih-Efendiev-Maris, 2020)

Assume similar properties for initial conditions. Then, there exist $\overline{u}_1, \overline{u}_2 \in L^2(0, T; H^1_0(D)) \cap C([0, T]; L^2(D))$ such that $u_1^{\varepsilon}, u_2^{\varepsilon}$ converge in probability to $\overline{u}_1, \overline{u}_2$:

$$\begin{cases} \frac{\partial \overline{u}_{1}}{\partial t} = \operatorname{div}\left(\overline{A}_{1}\nabla\overline{u}_{1}\right) + \overline{\alpha}(g_{1}(\overline{u}_{1},\overline{u}_{2}),g_{2}(\overline{u}_{1},\overline{u}_{2}))(\overline{u}_{2}-\overline{u}_{1}) + f_{1} \text{ in } D,\\ \frac{\partial \overline{u}_{2}}{\partial t} = \operatorname{div}\left(\overline{A}_{2}\nabla\overline{u}_{2}\right) + \overline{\alpha}(g_{1}(\overline{u}_{1},\overline{u}_{2}),g_{2}(\overline{u}_{1},\overline{u}_{2}))(\overline{u}_{1}-\overline{u}_{2}) + f_{2} \text{ in } D,\\ + \text{ initial conditions, boundary conditions,} \end{cases}$$

$$(21)$$

We need to pass to the limit in $\ensuremath{\varepsilon}$ on the variational formulation

$$\int_{D} u^{\varepsilon}(t)\phi - \int_{D} u_{0}^{\varepsilon}\phi + \int_{0}^{t} \int_{D} A^{\varepsilon} \nabla u^{\varepsilon}(s) \nabla \phi + \int_{0}^{t} \int_{D} \alpha^{\varepsilon}(v^{\varepsilon}) u^{\varepsilon} \phi$$
$$= \int_{0}^{t} \int_{D} f(s)\phi,$$

Here, we use tightness arguments and pass to the limit in distribution only. After changing the space of probability, the sequence u^{ε} given by Skorokhod theorem converges a.s. to \overline{u} strongly in $L^2(0, T; H^1_0(D))$

$$\int_{0}^{t} \int_{D} \alpha^{\varepsilon} (v^{\varepsilon}) u^{\varepsilon} \phi = S_{1}^{\varepsilon} + S_{2}^{\varepsilon} + S_{3}^{\varepsilon}$$
$$S_{1}^{\varepsilon} = \int_{0}^{T} \int_{D} (\alpha^{\varepsilon} (v^{\varepsilon}(t)) - \overline{\alpha^{\varepsilon}} (u^{\varepsilon}(t))) u^{\varepsilon}(t) \phi dx dt,$$
$$S_{2}^{\varepsilon} = \int_{0}^{T} \int_{D} (\overline{\alpha^{\varepsilon}} (u^{\varepsilon}(t)) u^{\varepsilon}(t) - \overline{\alpha^{\varepsilon}} (\overline{u}(t)) \overline{u}(t)) \phi dx dt,$$
$$S_{3}^{\varepsilon} = \int_{0}^{T} \int_{D} (\overline{\alpha^{\varepsilon}} (\overline{u}(t)) \overline{u}(t) - \overline{\alpha} (\overline{u}(t)) \overline{u}(t)) \phi dx dt.$$

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Fix n^{ε} a positive integer and let $\delta^{\varepsilon} = \frac{T}{n^{\varepsilon}}$. We define \tilde{u}^{ε} as the piecewise constant function:

$$\widetilde{u}^{\varepsilon}(t) = u^{\varepsilon}(k\delta^{\varepsilon}) \text{ for } t \in [k\delta^{\varepsilon}, (k+1)\delta^{\varepsilon}).$$
 (22)

We define also the sequence $\widetilde{\nu}^{\varepsilon}$ as the solution of:

$$\left\{ egin{array}{ll} d\widetilde{v}^arepsilon(t,x) &= -rac{1}{arepsilon}(\widetilde{v}^arepsilon(t,x) - \widetilde{u}^arepsilon(t,x))dt + \sqrt{rac{Q}{arepsilon}}dW(t,x), \ \widetilde{v}^arepsilon(0,x) &= v_0^arepsilon(x). \end{array}
ight.$$

A simple calculation shows that

$$\lim_{\delta^{\varepsilon} \to 0} \|\widetilde{u}^{\varepsilon} - u^{\varepsilon}\|_{L^{\infty}(0,T;L^{2}(D))} = 0,$$
(23)

so we also have that

$$\lim_{\delta^{\varepsilon} \to 0} \|\widetilde{v}^{\varepsilon} - v^{\varepsilon}\|_{L^{\infty}(0,T;L^{2}(D))} = 0,$$
(24)

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Now

$$\begin{split} &\int_{0}^{T}\int_{D}\left(\alpha^{\varepsilon}(v^{\varepsilon}(t))-\overline{\alpha}^{\varepsilon}(u^{\varepsilon}(t))\right)\phi^{\varepsilon}(t)dxdt\\ &-\int_{0}^{T}\int_{D}\left(\alpha^{\varepsilon}(\widetilde{v}^{\varepsilon}(t))-\overline{\alpha}^{\varepsilon}(\widetilde{u}^{\varepsilon}(t))\right)\phi^{\varepsilon}(t)dxdt=\\ &\int_{0}^{T}\int_{D}\phi^{\varepsilon}(t)\left(\alpha^{\varepsilon}(v^{\varepsilon}(t))-\alpha^{\varepsilon}(\widetilde{v}^{\varepsilon}(t))\right)dxdt\\ &+\int_{0}^{T}\int_{D}\phi^{\varepsilon}(t)\left(\overline{\alpha}^{\varepsilon}(\widetilde{u}^{\varepsilon}(t))-\overline{\alpha}^{\varepsilon}(u^{\varepsilon}(t))\right)dxdt,\\ &\rightarrow 0 \end{split}$$

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$$\begin{split} &\int_0^T \int_D \left(\alpha^{\varepsilon}(\widetilde{v}^{\varepsilon}(t)) - \overline{\alpha}^{\varepsilon}(\widetilde{u}^{\varepsilon}(t))\right) \phi^{\varepsilon}(t) dx dt \\ &= \sum_{k=0}^{n^{\varepsilon}-1} \int_{k\delta^{\varepsilon}}^{(k+1)\delta^{\varepsilon}} \int_D \left(\alpha^{\varepsilon}(\widetilde{v}^{\varepsilon}(t)) - \overline{\alpha}^{\varepsilon}(\widetilde{u}^{\varepsilon}(t))\right) \phi^{\varepsilon}(t) dx dt. \end{split}$$

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So, given the estimates uniform estimates for $u^\varepsilon,$ and choosing the δ^ε appropriately we can get that

 $\lim_{\varepsilon\to 0}\mathbb{E}\left|S_1^{\varepsilon}\right|=0.$

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For the convergence of $S_3^{arepsilon}$, we used the homogenization results

• G. Allaire (1991), Homogenization of the Navier-Stokes Equations with a Slip Boundary Condition. For any $t \in [0, T]$, $F_t^{\varepsilon} : L^2(D) \to L^2(D)$,

$$F_t^{\varepsilon}(z)(x) = \left(\alpha\left(\frac{x}{\varepsilon}, z(x)\right) - \int_Y \alpha(y, z(x))\right) u(t, x).$$

By a density argument, we show that: for any $z \in L^2(D)$, for every $t \in [0, T]$ and a.e. $\omega \in \Omega$,

$$\lim_{\varepsilon \to 0} F_t^{\varepsilon}(z) = 0 \quad \text{in} \quad L^2(D), \text{ weakly}.$$

The sequence being also uniformly bounded by $\|\overline{u}\|_{L^{\infty}(\Omega; C([0,T];L^{2}(D)))}$, Vitali's convergence theorem implies

$$\lim_{\varepsilon\to 0}\int_{L^2(D)}F_t^\varepsilon(z)d\mu^{\overline{u}(t)}(z)=0 \text{ in } L^2(D),$$

which can be rewritten as

$$\lim_{\varepsilon \to 0} \overline{\alpha^{\varepsilon}}(\overline{u}(t))\overline{u}(t) - \overline{\alpha}(\overline{u}(t))\overline{u}(t) = 0 \text{ in } L^2(D).$$

This implies that \mathbb{P} a.s. and for every $t \in [0, T]$

$$\lim_{\varepsilon \to 0} \int_D \left(\overline{\alpha^{\varepsilon}}(\overline{u}(t)) \overline{u}(t) - \overline{\alpha}(\overline{u}(t)) \overline{u}(t) \right) \phi \psi'(t) dx = 0.$$

The sequence being also uniformly bounded by $c \|\overline{u}\|_{L^{\infty}(\Omega, C([0, T]; L^{2}(D)))} \|\phi\|_{L^{\infty}(D)} \|\psi'\|_{L^{\infty}[0, T]}$. We apply the bounded convergence theorem and integrate over $\Omega \times [0, T]$ and get that

$$\lim_{\varepsilon\to 0}\mathbb{E}\left|S_3^{\varepsilon}\right|=0.$$

The convergence of S_2^{ε} is simpler:

$$\mathbb{E} |S_2^{\varepsilon}| \leq c \|\phi\|_{L^{\infty}(D)} \|\psi\|_{L^{\infty}[0,T]} \mathbb{E} \|u^{\varepsilon} - \overline{u}\|_{L^1(0,T;H^1_0(D)))}.$$

implies that

$$\lim_{\varepsilon\to 0}\mathbb{E}\left|S_2^{\varepsilon}\right|=0.$$

Combining the convergences of S_1^{ε} , S_2^{ε} and S_3^{ε} we get that

$$\lim_{\varepsilon \to 0} \mathbb{E} \left| \int_0^T \int_D \left(\alpha^{\varepsilon} (v^{\varepsilon}(t)) u^{\varepsilon}(t) - \overline{\alpha}(\overline{u}(t)) \overline{u}(t) \right) \phi dx dt \right| = 0.$$

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- Tackle the full diffusion problem
- Tackle the case of coefficient dependent on time, the non-autonomous case
- Generalize to the case of SPDEs for the particle equations
- Find some rate of convergence. This is related to better convergence, like convergence in mean.

- H. Bessaih, Y. Efendiev, F. Maris, Homogenization of Brinkman flows in heterogenous dynamic media, SPDE: Analysis and Computations, 3 (2015), no 4, 479–505.
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