



Weierstrass Institute for
Applied Analysis and Stochastics



Error estimates for elliptic and parabolic equations with oscillating coefficients

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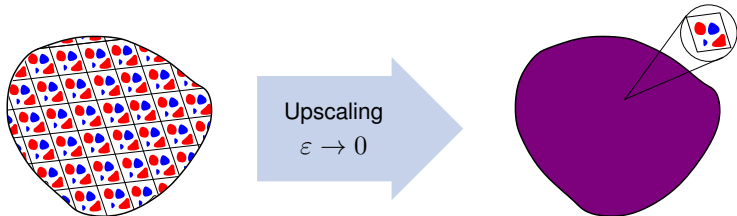
- 1 Introduction: periodic homogenization**
- 2 Two-scale convergence**
- 3 Two-scale homogenization of reaction-diffusion systems**
- 4 Error estimates for elliptic equations**

- 1 Introduction: periodic homogenization**
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Set-up: Given is a problem (P_ε) involving effects on microscopic scales, where $\varepsilon > 0$ denotes the quotient $\varepsilon = \frac{\text{micro-length}}{\text{macro-length}}$.

Difficulties: Numerical and analytical treatments are very challenging. What happens if ε tends to zero?

Task: Find an effective model problem (P_0), which represents the properties of the original microscopic system well.



Let us consider the linear elliptic equation



$$\begin{aligned} -\operatorname{div}(a_\varepsilon \nabla u_\varepsilon) &= f && \text{in } \Omega, \\ u_\varepsilon &= 0 && \text{on } \partial\Omega. \end{aligned} \quad (\mathbf{P}_\varepsilon)$$

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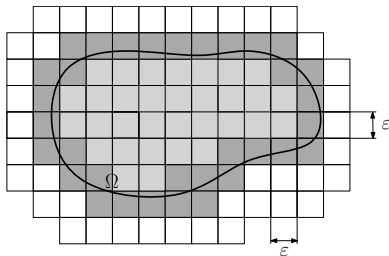


$$\begin{aligned} -\operatorname{div}(a_\varepsilon \nabla u_\varepsilon) &= f && \text{in } \Omega, \\ u_\varepsilon &= 0 && \text{on } \partial\Omega. \end{aligned} \quad (\mathbf{P}_\varepsilon)$$

The coefficients a_ε are of the form

$$a_\varepsilon(x) := a\left(\frac{x}{\varepsilon}\right)$$

for a given matrix $a(y) \in \mathbb{R}_{\text{sym}}^{d \times d}$ which is Y -periodic and positive definite.



Notation:

$\Omega \subset \mathbb{R}^d$ macroscopic domain

$Y = (0, 1)^d$ unit-cell

$Y_{\text{per}} = \mathbb{R}^d / \mathbb{Z}^d$ torus

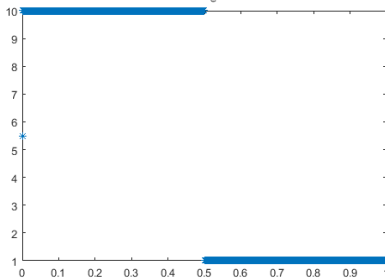
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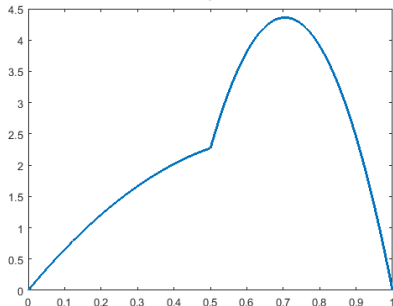
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Example: $\Omega = (0, 1)$ one dimensional

coefficient a_ε for $\varepsilon = 1$



solution u_ε for $\varepsilon = 1$



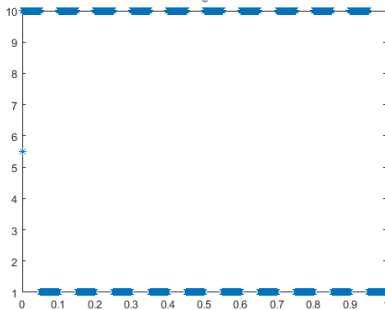
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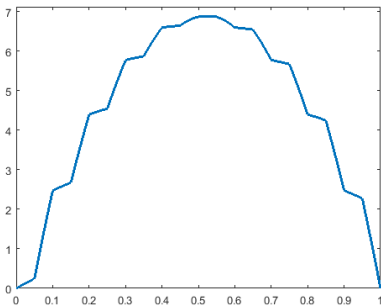
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coefficient a_ε for $\varepsilon = 0.1$



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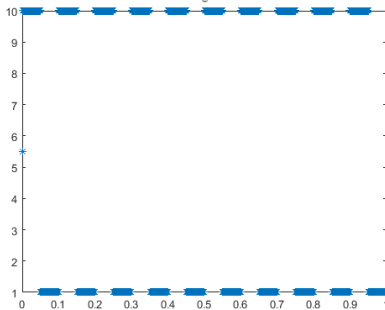
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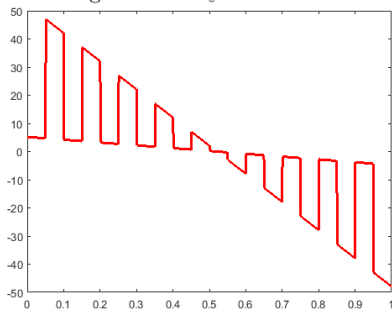
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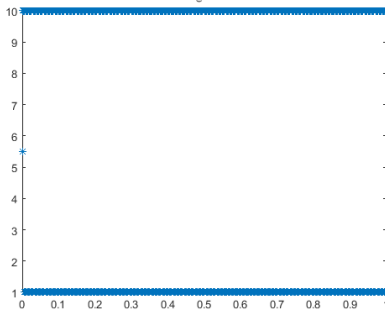
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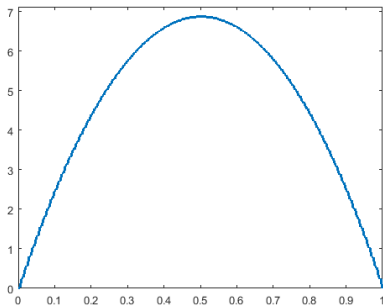
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Example: $\Omega = (0, 1)$ one dimensional

coefficient a_ε for $\varepsilon = 0.01$



solution u_ε for $\varepsilon = 0.01$



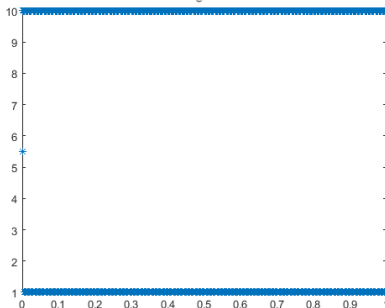
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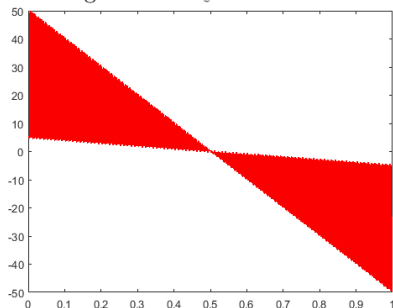
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coefficient a_ε for $\varepsilon = 0.01$



gradient ∇u_ε for $\varepsilon = 0.01$



The homogenized equation reads



$$\begin{aligned} -\operatorname{div}(a_{\text{eff}} \nabla u) &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega. \end{aligned} \tag{P_0}$$

Example: $\Omega = (0, 1)$ one dimensional

The effective coefficient a_{eff} is the harmonic mean, i.e.

$$a_{\text{eff}} = \left(\int_Y \frac{1}{a(y)} dy \right)^{-1}.$$

The homogenized equation reads



$$\begin{aligned} -\operatorname{div}(a_{\text{eff}} \nabla u) &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega. \end{aligned} \quad (\text{P}_0)$$

The effective matrix $a_{\text{eff}} \in \mathbb{R}_{\text{sym}}^{d \times d}$ is given by solving the [unit-cell problem](#)

$$\xi \cdot a_{\text{eff}} \xi = \min_{\varphi \in \mathbf{H}_{\text{per}}^1(Y)} \int_Y (\nabla_y \varphi + \xi) \cdot a(y) (\nabla_y \varphi + \xi) \, dy \quad \forall \xi \in \mathbb{R}^d.$$

Ansatz of power series in ε for u_ε

$$u_\varepsilon(x) \approx u_0(x, \frac{x}{\varepsilon}) + \varepsilon u_1(x, \frac{x}{\varepsilon}) + \varepsilon^2 u_2(x, \frac{x}{\varepsilon}) + \dots$$

Inserting u_ε into (P_ε) and sorting for powers of ε gives

$$u_\varepsilon(x) = u(x) + \varepsilon U(x, \frac{x}{\varepsilon}) + O(\varepsilon^2),$$

where u solves the homogenized equation (P_0) and the corrector U is given via

$$U(x, y) = \sum_{i=1}^d \frac{\partial u}{\partial x_i}(x) \cdot z_i(y).$$

Here $z_i \in H_{\text{per}}^1(Y)$ with $\int_Y z_i \, dy = 0$ solves the local problem

$$\operatorname{div}_y (a(y)(\nabla_y z_i(y) + e_i)) = 0 \quad \text{in } Y_{\text{per}}.$$

($z_i =$ minimizers of unit-cell problem for $\xi = e_i$.)

Ansatz of power series in ε for u_ε

$$u_\varepsilon(x) \approx u_0(x, \frac{x}{\varepsilon}) + \varepsilon u_1(x, \frac{x}{\varepsilon}) + \varepsilon^2 u_2(x, \frac{x}{\varepsilon}) + \dots$$

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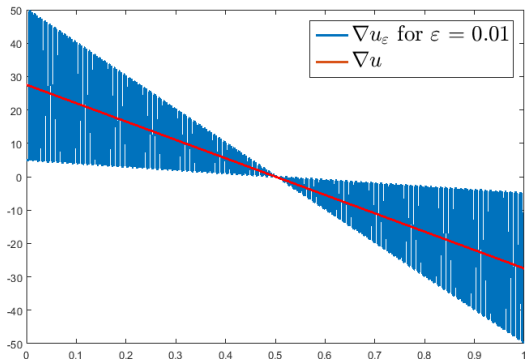
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One can prove

$$u_\varepsilon \rightarrow u \quad \text{and} \quad \nabla u_\varepsilon \rightarrow \nabla u + \nabla_y U(x, y) \quad \text{in the two-scale sense.}$$

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Definition [Nguetseng 1989, Allaire 1992]

We say $u_\varepsilon \rightharpoonup U$ in the two-scale sense, if

$$\int_{\Omega} u_\varepsilon(x) \Phi(x, \frac{x}{\varepsilon}) dx \rightarrow \int_{\Omega \times Y} U(x, y) \Phi(x, y) dx dy$$

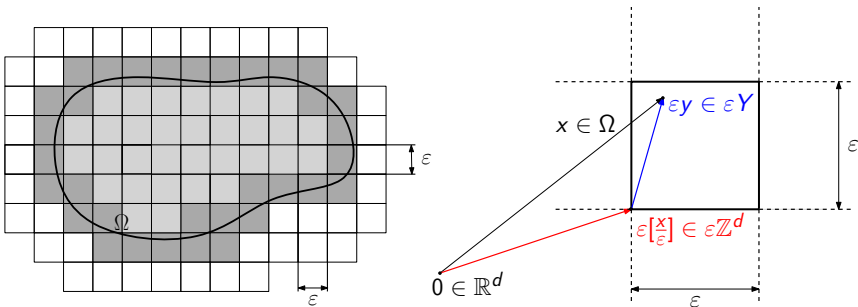
for all $\Phi \in C_c^\infty(\Omega \times Y_{\text{per}})$.

- This is a weak notion of convergence.
- Strong two-scale convergence formulation via periodic unfolding operator \mathcal{T}_ε .
- The periodic unfolding method enables error estimates.

Definition [Cioranescu et al. 2002]

The **periodic unfolding operator** $\mathcal{T}_\varepsilon : L^2(\Omega) \rightarrow L^2(\Omega \times Y_{\text{per}})$ is defined via

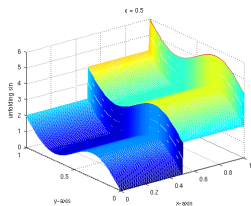
$$(\mathcal{T}_\varepsilon u)(x, y) = u\left(\varepsilon\left[\frac{x}{\varepsilon}\right] + \varepsilon y\right).$$



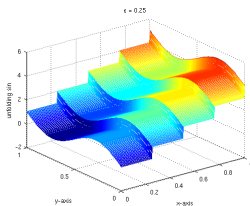
$$(\mathcal{T}_\varepsilon u)(x, y) = u\left(\varepsilon\left[\frac{x}{\varepsilon}\right] + \varepsilon y\right)$$

Example: strong two-scale convergence of oscillating functions

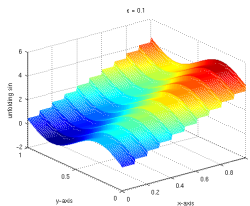
- $\Omega = Y = (0, 1)$
- $u_\varepsilon(x) = \sin(2\pi \frac{x}{\varepsilon}) + 4x$
- $(\mathcal{T}_\varepsilon u_\varepsilon)(x, y) = \sin(2\pi y) + 4(\varepsilon[\frac{x}{\varepsilon}] + \varepsilon y)$ is not Y -periodic



$\varepsilon = 0.5$



$\varepsilon = 0.25$



$\varepsilon = 0.1$

- Limit $\lim_{\varepsilon \rightarrow 0} (\mathcal{T}_\varepsilon u_\varepsilon)(x, y) = \sin(2\pi y) + 4x$ is Y -periodic

$$(\mathcal{T}_\varepsilon u)(x, y) = u\left(\varepsilon \left[\frac{x}{\varepsilon}\right] + \varepsilon y\right)$$

Definition (weak and strong two-scale convergence) [Mielke/Timofte 2007]

Let $(u_\varepsilon)_{\varepsilon>0}$ be a sequence in $L^2(\Omega)$.

$$\begin{array}{l}
 u_\varepsilon \xrightarrow{2w} U \quad \text{in } L^2(\Omega \times Y_{\text{per}}) \quad : \stackrel{\text{Def}}{\iff} \quad \mathcal{T}_\varepsilon u_\varepsilon \rightharpoonup U \quad \text{in } L^2(\Omega \times Y_{\text{per}}) \\
 u_\varepsilon \xrightarrow{2s} U \quad \text{in } L^2(\Omega \times Y_{\text{per}}) \quad : \stackrel{\text{Def}}{\iff} \quad \mathcal{T}_\varepsilon u_\varepsilon \rightarrow U \quad \text{in } L^2(\Omega \times Y_{\text{per}})
 \end{array}$$

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Consider for $\varepsilon > 0$ the following **system of coupled reaction-diffusion equations** with **slow diffusion** and no-flux boundary conditions in $[0, T] \times \Omega$,

$$\begin{aligned} \dot{u}_\varepsilon &= \operatorname{div}\left(D_1\left(\frac{x}{\varepsilon}\right)\nabla u_\varepsilon\right) + F_1\left(\frac{x}{\varepsilon}, u_\varepsilon, v_\varepsilon\right), \\ \dot{v}_\varepsilon &= \operatorname{div}\left(\varepsilon^2 D_2\left(\frac{x}{\varepsilon}\right)\nabla v_\varepsilon\right) + F_2\left(\frac{x}{\varepsilon}, u_\varepsilon, v_\varepsilon\right). \end{aligned} \quad (\mathbf{P}_\varepsilon)$$

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- Many applied math publications on systems with slow diffusion, i.e.
[Hornung/Jäger/Mikelić 1994, Peter/Böhm 2008, Hanke 2011, Mielke/Rohan 2013, Graf/Peter 2014, Jäger/Neuss-Radu 2007, Ptashnyk/Roose 2010, Eck 2004, Fatima et al. 2011, Muntean/van Noorden 2013].

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- Proof of $u_\varepsilon \rightarrow u$ and $v_\varepsilon \xrightarrow{2s} V$ in [Mielke/R./Thomas, NHM, 2014] for **well-prepared initial values** (\Rightarrow improved time-regularity for solutions), i.e.

$$\sup_{\varepsilon > 0} \|\operatorname{div}(\varepsilon^2 D_2(\frac{x}{\varepsilon})\nabla v_\varepsilon(0))\|_{L^2(\Omega)} < \infty.$$

Theorem ([R., PhD thesis, 2015])

We assume $u_\varepsilon(0) \rightarrow u(0)$ in $L^2(\Omega)$ and $v_\varepsilon(0) \xrightarrow{2s} V(0)$ in $L^2(\Omega \times Y_{\text{per}})$.

Then the solution $(u_\varepsilon, v_\varepsilon)$ of (P_ε) converges in the two-scale sense to (u, V) which solves the **effective two-scale model** (P_0) .

Macroscopic equation in $[0, T] \times \Omega$:

$$\dot{u}(t, x) = \underbrace{\operatorname{div}(D_{\text{eff}} \nabla u(t, x))}_{\text{macro-diffusion}} + \underbrace{\int_Y F_1(y, u(t, x), V(t, x, y)) \, dy}_{\text{macro-reaction}}$$

Two-scale equation in $[0, T] \times Y_{\text{per}}$, $\Omega \sim$ "set of parameter": (P₀)

$$\dot{V}(t, x, y) = \underbrace{\operatorname{div}_y(D_2(y) \nabla_y V(t, x, y))}_{\text{micro-diffusion}} + \underbrace{F_2(y, u(t, x), V(t, x, y))}_{\text{two-scale reaction}}.$$

(1) Unfolding of the original problem (P_ε) to the two-scale space $\Omega \times Y_{\text{per}} \dots$

The **folding operator** $\mathcal{F}_\varepsilon : L^2(\Omega \times Y_{\text{per}}) \rightarrow L^2(\Omega)$ is defined via

$$(\mathcal{F}_\varepsilon V)(x) := \int_{\varepsilon([\frac{x}{\varepsilon}] + Y)} V(z, \{\frac{x}{\varepsilon}\}) \, dz.$$

$$\implies \mathcal{F}_\varepsilon V \xrightarrow{2s} V \text{ in } L^2(\Omega \times Y_{\text{per}}) \text{ and } \mathcal{F}_\varepsilon = \mathcal{T}_\varepsilon^*.$$

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(2) Finding a test function for (P_ε) ...

$$V(x, \frac{x}{\varepsilon}) \text{ and } (\mathcal{F}_\varepsilon V)(x) \text{ are not admissible.}$$

The **gradient folding operator** $\mathcal{G}_\varepsilon : L^2(\Omega; H_{\text{per}}^1(Y)) \rightarrow H^1(\Omega)$ is defined as the solution $\mathcal{G}_\varepsilon V := \hat{v}_\varepsilon$ of the elliptic problem [Mielke/Timofté 2007, Hanke 2011]

$$\int_{\Omega} (\hat{v}_\varepsilon - \mathcal{F}_\varepsilon V) \cdot \varphi + (\varepsilon \nabla \hat{v}_\varepsilon - \mathcal{F}_\varepsilon(\nabla_y V)) : \varepsilon \nabla \varphi \, dx = 0 \quad \forall \varphi \in H^1(\Omega).$$

$$\implies \mathcal{G}_\varepsilon V \xrightarrow{2s} V \text{ and } \varepsilon \nabla(\mathcal{G}_\varepsilon V) \xrightarrow{2s} \nabla_y V \text{ in } L^2(\Omega \times Y_{\text{per}}). \quad [\text{Hanke 2011}]$$

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(3) Finding a test function for (P_0) ... $\mathcal{T}_\varepsilon v_\varepsilon$ is not Y -periodic.

Theorem (R., JPCS, 2016)

Let $(u_\varepsilon, v_\varepsilon)$ and (u, V) be the solution of (P_ε) and (P_0) , respectively. If the initial values are well-prepared and satisfy

$$\exists c \geq 0 : \quad \|u_\varepsilon(0) - u(0)\|_{L^2(\Omega)} + \|\mathcal{T}_\varepsilon v_\varepsilon(0) - V(0)\|_{L^2(\Omega \times Y)} \leq \varepsilon^{1/4} c,$$

then there exists a constant $C \geq 0$ such that

$$\begin{aligned} & \|u_\varepsilon - u\|_{C([0,T];L^2(\Omega))} + \|\mathcal{T}_\varepsilon(\nabla u_\varepsilon) - [\nabla u + \nabla_y U]\|_{L^2(0,T;L^2(\Omega \times Y))} + \\ & \|\mathcal{T}_\varepsilon v_\varepsilon - V\|_{C([0,T];L^2(\Omega \times Y))} + \|\mathcal{T}_\varepsilon(\varepsilon \nabla v_\varepsilon) - \nabla_y V\|_{L^2(0,T;L^2(\Omega \times Y))} \leq \varepsilon^{1/4} C. \end{aligned}$$

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- Work in progress (next section): estimates of order $O(\varepsilon^{1/2})$.
- Estimates for non well-prepared initial values of order $O(\varepsilon^{1/6})$ in [R., PhD thesis, 2015].

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Given: elliptic equation with not exactly ε -periodic coefficients

$$v_\varepsilon - \operatorname{div} \left(\varepsilon^2 \mathbb{A} \left(x, \frac{x}{\varepsilon} \right) \nabla v_\varepsilon \right) = F_\varepsilon(x) \quad \text{in } \Omega \quad (\text{P}_\varepsilon)$$

supplemented with no-flux boundary conditions on $\partial\Omega$ and $F_\varepsilon(x) := (\mathcal{F}_\varepsilon \mathbb{F})(x)$.

Aim: prove error estimates under the minimal regularity assumptions

$$\mathbb{A} \in W^{1,\infty}(\Omega; L^\infty(Y_{\text{per}})) \quad \text{and} \quad \mathbb{F} \in H^1(\Omega; L^2(Y_{\text{per}})).$$

Theorem (unpublished)

Let $v_\varepsilon \in H^1(\Omega)$ solve (P_ε) . Then there exists $V \in H^1(\Omega; H^1_{\text{per}}(Y))$ solving

$$V - \operatorname{div}_y(\mathbb{A} \nabla_y V) = \mathbb{F} \quad \text{in } \Omega \times Y_{\text{per}} \quad (\text{P}_0)$$

and a constant $C > 0$ such that

$$\| \mathcal{T}_\varepsilon v_\varepsilon - V \|_{L^2(\Omega; H^1(Y))} \leq \varepsilon^{1/2} C.$$

Step 1: Testing (P_0) with $\mathcal{T}_\varepsilon\varphi \in L^2(\Omega; H^1(Y)) \not\supseteq L^2(\Omega; H^1_{\text{per}}(Y))$ is not allowed; thus we obtain the **periodicity defect error** $\Delta_{\text{per}}^\varepsilon$

$$\left| \int_{\Omega \times Y} \mathbb{A} \nabla_y V \cdot \nabla_y (\mathcal{T}_\varepsilon \varphi) + V \mathcal{T}_\varepsilon \varphi - \mathbb{F} \mathcal{T}_\varepsilon \varphi \, dx \, dy \right| \leq \Delta_{\text{per}}^\varepsilon \|\varphi\|_\varepsilon,$$

where $\|\varphi\|_\varepsilon := \|\varphi\|_{L^2(\Omega)} + \varepsilon \|\nabla \varphi\|_{L^2(\Omega)}$.

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where $\|\varphi\|_\varepsilon := \|\varphi\|_{L^2(\Omega)} + \varepsilon \|\nabla \varphi\|_{L^2(\Omega)}$.

Step 2: Using $\mathcal{F}_\varepsilon = \mathcal{T}_\varepsilon^*$ and $\nabla_y (\mathcal{T}_\varepsilon \varphi) = \mathcal{T}_\varepsilon (\varepsilon \nabla \varphi)$ as well as estimating the **approximation error** $\Delta_{\text{app}}^\varepsilon$ for $A_\varepsilon - \mathcal{F}_\varepsilon \mathbb{A}$ gives

$$\left| \int_{\Omega} A_\varepsilon \mathcal{F}_\varepsilon (\nabla_y V) \cdot \varepsilon \nabla \varphi + \mathcal{F}_\varepsilon V \varphi - F_\varepsilon \varphi \, dx \right| \leq \Delta_{\text{per,app}}^\varepsilon \|\varphi\|_\varepsilon.$$

Step 1: Testing (P_0) with $\mathcal{T}_\varepsilon \varphi \in L^2(\Omega; H^1(Y)) \not\subseteq L^2(\Omega; H^1_{\text{per}}(Y))$ is not allowed; thus we obtain the **periodicity defect error** $\Delta_{\text{per}}^\varepsilon$

$$\left| \int_{\Omega \times Y} \mathbb{A} \nabla_y V \cdot \nabla_y (\mathcal{T}_\varepsilon \varphi) + V \mathcal{T}_\varepsilon \varphi - \mathbb{F} \mathcal{T}_\varepsilon \varphi \, dx \, dy \right| \leq \Delta_{\text{per}}^\varepsilon \|\varphi\|_\varepsilon,$$

where $\|\varphi\|_\varepsilon := \|\varphi\|_{L^2(\Omega)} + \varepsilon \|\nabla \varphi\|_{L^2(\Omega)}$.

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Step 3: Testing (P_ε) with $\varphi_\varepsilon = v_\varepsilon - \mathcal{G}_\varepsilon V \in H^1(\Omega)$ is admissible. By controlling the **folding mismatch** $\Delta_{\text{fold}}^\varepsilon$ of $\mathcal{F}_\varepsilon V - \mathcal{G}_\varepsilon V$ and $\mathcal{F}_\varepsilon (\nabla_y V) - \varepsilon \nabla (\mathcal{G}_\varepsilon V)$, we obtain

$$\alpha \|v_\varepsilon - \mathcal{G}_\varepsilon V\|_\varepsilon^2 \leq \Delta_{\text{per,app,fold}}^\varepsilon \|v_\varepsilon - \mathcal{G}_\varepsilon V\|_\varepsilon.$$

It remains: quantitative estimates for the error terms

- approximation error: $\Delta_{\text{app}}^\varepsilon \sim O(\varepsilon^{1/2}) \Rightarrow$ easy
- periodicity defect of $\mathcal{T}_\varepsilon \varphi$ for arbitrary $\varphi \in H^1(\Omega)$: $\Delta_{\text{per}}^\varepsilon \sim O(\varepsilon^{1/2})$
 \Rightarrow estimates exist [Griso 2004/05]
- folding mismatch between \mathcal{F}_ε and \mathcal{G}_ε : $\Delta_{\text{fold}}^\varepsilon \sim O(\varepsilon^{1/2}) \Rightarrow$ new estimate

Overall, we arrive at

$$\alpha \|v_\varepsilon - \mathcal{G}_\varepsilon V\|_\varepsilon^2 \leq \varepsilon^{1/2} C \|v_\varepsilon - \mathcal{G}_\varepsilon V\|_\varepsilon.$$



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□

Related results in the literature:

- Error estimates for slow & classical diffusion based on asymptotic expansion [Eck 2004, Muntean/van Noorden 2013]
- Unfolding based error estimates for classical diffusion [Griso 2004/05, Fatima/Muntean/Ptashnyk 2012]

Proposition [R., PhD thesis, 2015]

For every $V \in H^1(\Omega; H_{\text{per}}^1(Y))$ it holds

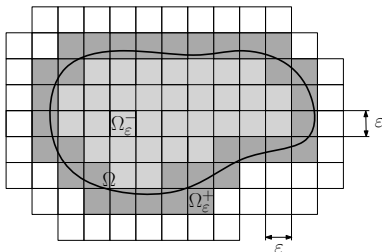
$$\|\mathcal{G}_\varepsilon V - \mathcal{F}_\varepsilon V\|_{L^2(\Omega)} + \|\varepsilon \nabla(\mathcal{G}_\varepsilon V) - \mathcal{F}_\varepsilon(\nabla_y V)\|_{L^2(\Omega)} \leq (\varepsilon + \varepsilon^{1/2})C\|V\|.$$

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Outline of proof: Step 1. Derive boundary estimates of order $O(\varepsilon^{1/2})$.



Assume $\Omega = \Omega_\varepsilon^+$ and redefine \mathcal{F}_ε and \mathcal{G}_ε on Ω_ε^+ .

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Step 2. Assume $V(x, y) = w(x) \cdot z(y)$ is a product.

- Introduce the scale-splitting operator \mathcal{Q}_ε . [Cioranescu/Damlamian/Griso 2008]
- Use that $x \mapsto (\mathcal{Q}_\varepsilon w)(x) \cdot z(\frac{x}{\varepsilon})$ is an admissible test function in $H^1(\Omega)$.

Proposition [R., PhD thesis, 2015]

For every $V \in H^1(\Omega; H^1_{\text{per}}(Y))$ it holds

$$\| \mathcal{G}_\varepsilon V - \mathcal{F}_\varepsilon V \|_{L^2(\Omega)} + \| \varepsilon \nabla(\mathcal{G}_\varepsilon V) - \mathcal{F}_\varepsilon(\nabla_y V) \|_{L^2(\Omega)} \leq (\varepsilon + \varepsilon^{1/2}) C \|V\|.$$

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Note that for **classical diffusion and exactly periodic** coefficients we have

$$U(x, y) = \sum_{i=1}^d \frac{\partial u}{\partial x_i}(x) \cdot z_i(y).$$

Proposition [R., PhD thesis, 2015]

For every $V \in H^1(\Omega; H_{\text{per}}^1(Y))$ it holds

$$\| \mathcal{G}_\varepsilon V - \mathcal{F}_\varepsilon V \|_{L^2(\Omega)} + \| \varepsilon \nabla(\mathcal{G}_\varepsilon V) - \mathcal{F}_\varepsilon(\nabla_y V) \|_{L^2(\Omega)} \leq (\varepsilon + \varepsilon^{1/2}) C \|V\|.$$

Outline of proof: Step 1. Derive boundary estimates of order $O(\varepsilon^{1/2})$.

Step 2. Assume $V(x, y) = w(x) \cdot z(y)$ is a product.

Step 3. Prove the estimate for general $V(x, y)$.

- For an orthonormal basis $\{\Phi_i\}$ of $H_{\text{per}}^1(Y)$ use the decomposition

$$V(x, y) = \sum_{i=1}^{\infty} v_i(x) \cdot \Phi_i(y) \quad \text{with} \quad v_i(x) = \int_Y V(x, y) \cdot \Phi_i(y) \, dy.$$

- Show that $\Phi_i \perp \Phi_j$ in $H_{\text{per}}^1(Y)$ implies $\mathcal{G}_\varepsilon \Phi_i \perp \mathcal{G}_\varepsilon \Phi_j$ in $H^1(\Omega)$ for $i \neq j$.
- Exploit [Step 2](#) with $w = v_i$ and $z = \Phi_i$. □

Classical diffusion: admissible test function for $(P_\varepsilon)_{\text{class}}$ is $\varphi_\varepsilon = u_\varepsilon - [u + \varepsilon \mathcal{G}_\varepsilon U]$

$$\frac{1}{2} \frac{d}{dt} \|u_\varepsilon - u\|_{L^2(\Omega)}^2 = \int_{\Omega} (\dot{u}_\varepsilon - \dot{u}) \cdot \varphi_\varepsilon + \underbrace{(\dot{u}_\varepsilon - \dot{u}) \cdot \varepsilon \mathcal{G}_\varepsilon U}_{\sim O(\varepsilon)} dx.$$

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Slow diffusion: We require improved time-regularity, i.e. $\sup_{\varepsilon > 0} \|\dot{v}_\varepsilon\|_{L^2(\Omega)} < \infty$.

An admissible test function for $(P_\varepsilon)_{\text{slow}}$ is $\varphi_\varepsilon = v_\varepsilon - \mathcal{G}_\varepsilon V$

$$\frac{1}{2} \frac{d}{dt} \|v_\varepsilon - \mathcal{F}_\varepsilon V\|^2 = \int_{\Omega} (\dot{v}_\varepsilon - \mathcal{F}_\varepsilon \dot{V}) \cdot \varphi_\varepsilon + \underbrace{(\dot{v}_\varepsilon - \mathcal{F}_\varepsilon \dot{V}) \cdot (\mathcal{G}_\varepsilon V - \mathcal{F}_\varepsilon V)}_{\sim O(\varepsilon + \varepsilon^{1/2}) \text{ folding mismatch}} dx.$$

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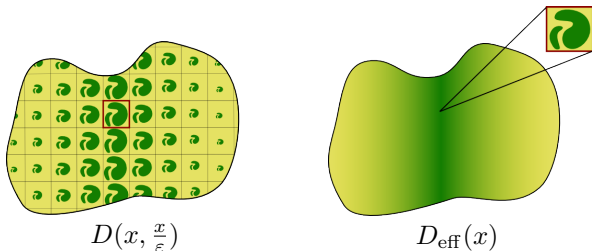
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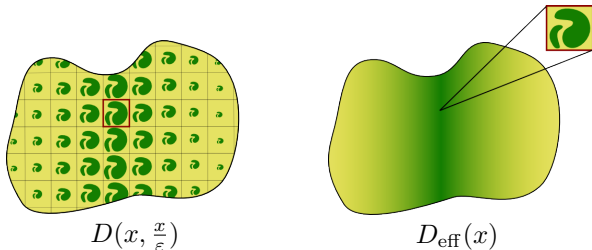
- To obtain the convergence rate $\varepsilon^{1/2}$, carry out estimations on Ω_ε^+ such that $\Delta_{\text{fold}}^\varepsilon \sim O(\varepsilon)$.

- Two-scale convergence “makes” asymptotic expansion rigorous.
- Not exactly periodic microstructures are possible.



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- For homogenization without error estimates discontinuities of the data w.r.t. $x \in \Omega$ are allowed, too.

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Thank you for your attention.